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1 Regular Article 2 Simplified Estimation of Oxygen Consumption During Treadmill Walking Based 3 on Ankle Accelerometry and Velocity 4 Rei Nemoto^{1,2}, Tomoyuki Ito^{1,2,3},* Kimiko Ogawa^{2,4}, Hitomi Koyama^{1,2}, Takaaki 5 6 Hisaoka¹, Ryo Ito¹, Suzuyo Ohashi², Yasuo Mikami² 7 ¹ Department of Rehabilitation Medicine, Kyoto Tanabe Memorial Hospital, Kyoto, 8 9 Japan (1, Tanabe-Todae, Kyotanabe-city, Kyoto, 610-0331, Japan) 10 ² Department of Rehabilitation Medicine, Graduate School of Medical Science, Kyoto 11 Prefectural University of Medicine, Kyoto, Japan (465, Kawaramachi-Hirokoji, 12 Kamigyo-ku, Kyoto, 602-8566, Japan) ³ Faculty of Health Science, Aichi Gakuin University, Japan (12, Araike, Iwasaki-cho, 13 14 Nissin-city, Aichi, 470-0195, Japan) ⁴ Department of Clinical Nutrition, Kyoto Tanabe Central Hospital, Kyoto, Japan (6-1-6, 15 Tanabe-Chuo, Kyotanabe-city, Kyoto, 610-0334, Japan) 16

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Abstract

- We aimed to develop regression models for estimating oxygen consumption (VO₂,
- 25 ml·kg⁻¹·min⁻¹) during treadmill walking based on accelerations of the upper and lower
- 26 limbs and walking velocity, quantitatively assess the contribution of each sensor
- location, and validate the accuracy and practicality of a simplified model.
- Eighteen healthy adults with regular exercise habits (nine men, nine women)
- 29 participated in treadmill walking trials at varying speeds (3–6 km·h⁻¹; up to 5.5 km·h⁻¹
- 30 for women). Vector magnitude (VM) from triaxial accelerometers attached to both
- 31 wrists and both ankles was recorded simultaneously with VO₂ measurements from a
- 32 portable breath-by-breath gas analyzer. Multiple regression models were constructed
- using FootVM (ankle VM), HandVM (wrist VM), and walking velocity as predictors.
- FootVM alone showed a moderate correlation with VO_2 ($R^2 = 0.464$), but adding
- walking velocity substantially improved the model's accuracy (Model 2: $R^2 = 0.810$,
- 36 standard error of estimate = 1.25 ml·kg⁻¹·min⁻¹). Incorporating HandVM yielded only a
- 37 minimal, non-significant model fit improvement ($R^2 = 0.815$, $\triangle AIC = +18.4$, $\beta std =$
- 38 –0.06), with no meaningful statistical contribution. Bland–Altman analysis indicated
- 39 95% limits of agreement for estimation error within ±2.46 ml·kg⁻¹·min⁻¹, corresponding

- 40 to < 1 MET (3.5 ml·kg⁻¹·min⁻¹). These findings support the rational selection of a
- simplified model using only FootVM and walking velocity, which achieved a balance
- between high accuracy and practicality. The ability to estimate VO₂ precisely using only
- 43 ankle-mounted accelerometers highlights its potential for use in clinical and home-based
- 44 physical activity assessment.
- 46 **Keywords**: accelerometer, oxygen consumption, gait, wearable sensor, model
- 47 simplification

タイトル 48 足関節加速度と歩行速度に基づくトレッドミル歩行中の酸素消費量の簡易推定 49 50 51 著者名 根本 玲 1,2, 伊藤倫之 1,2,3,* 小川貴美子 2,4, 小山 瞳 1,2, 久岡 隆晃 1, 52 伊東 諒 1, 大橋鈴世 2, 三上靖夫 2 53 54 55 所属 √ 京都田辺記念病院リハビリテーション科(〒610-0331 京都府京田辺市田辺戸絶 1 56 番地) 57 2 京都府立医科大学大学院リハビリテーション医学(〒602-8566 京都市上京区河原 58 59 町通広小路上る梶井町 465) 60 3 愛知学院大学健康科学部健康科学科 (〒470-0195 愛知県日進市岩崎町阿良 61 池 12) ⁴ 京都田辺中央病院臨床栄養部(〒610-0334 京都府京田辺市田辺中央 6 丁目 1 62

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- 64 抄録
- 65 本研究では、トレッドミル歩行中の酸素摂取量(VO2、ml·kg-1·min-1)を、上下肢の加
- 66 速度および歩行速度に基づいて推定する回帰モデルを開発し、各センサー位置の寄与を
- 67 定量的に評価するとともに、簡素化モデルの精度と実用性を検証することを目的とした。
- 68 定期的に運動習慣のある健常成人 18 名 (男性 9 名、女性 9 名) が参加し、3~6
- 69 km/h (女性は最大 5.5 km/h) の異なる速度でトレッドミル歩行試験を実施した。両手関
- 70 節および両足関節に装着した3軸加速度計から得られるベクトルマグニチュード (VM)
- 71 と、携帯型呼気ガス分析装置による VO2測定を同時に記録した。FootVM(両足関節の
- 72 VM 合計値)、HandVM(両手関節の VM 合計値)、歩行速度を説明変数として、
- 73 複数の回帰モデルを構築した。
- 74 FootVM 単独では VO_2 と中等度の相関 $(R^2 = 0.464)$ を示したが、歩行速度を加えるこ
- 75 とでモデルの精度は大幅に向上した(モデル 2: R² = 0.810、推定標準誤差 = 1.25
- 76 ml·kg⁻¹·min⁻¹)。HandVM を追加してもモデル適合度の改善はごくわずかで統計的にも
- 77 有意ではなかった(R² = 0.815、ΔAIC = +18.4、β 標準化係数 = -0.06)。Bland-
- 78 Altman 解析では、推定誤差の 95%限界が±2.46 ml·kg⁻¹·min⁻¹の範囲にあり、1 MET
- 79 (3.5 ml·kg⁻¹·min⁻¹) 未満であった。
- 80 これらの結果から、FootVMと歩行速度のみを用いた簡素なモデルの合理的選択が支持さ

- 81 れ、高精度と実用性のバランスを実現していることが示された。足関節装着型加速度計の
- 82 みで VO2を高精度に推定できることは、臨床や在宅における身体活動評価への応用可能
- 83 性を示唆している。

Introduction

Estimating oxygen consumption (VO₂) and energy expenditure during walking is 86 87 crucial in fields such as rehabilitation, sports medicine, and the assessment of daily physical activity¹⁾. In recent years, the development of wearable devices has led to 88 89 growing interest in non-invasive and simple estimation methods using accelerometers²⁾. 90 Among these, vector magnitude (VM) derived from triaxial acceleration has been widely used as an indicator of physical activity intensity 3,4 . 91 92 Previous studies have primarily focused on estimating energy expenditure using accelerometers worn on the waist or thigh 4-6). However, VM characteristics vary 93 94 significantly depending on sensor placement. Wrist-worn sensors, in particular, are 95 susceptible to variation in arm swing and inter-individual differences, potentially 96 capturing movements not directly related to propulsion during walking, and thereby reducing prediction accuracy^{7,8)}. To address these limitations, some studies have 97 98 proposed models incorporating multiple sensor placements or additional physiological indices such as heart rate^{9,10)}. However, these approaches often require multiple devices 99 100 and complex data processing, limiting their practicality for clinical and daily use. 101 Therefore, a more practical approach may lie in identifying sensor placements that offer

locomotor activity, has been suggested as a promising site for measuring walkingrelated acceleration. Yet, few studies have systematically compared the contributions of

both predictive accuracy and simplicity. The ankle, which more directly reflects

upper and lower limb accelerometry to VO₂ estimation.

This study aimed to develop regression models for estimating oxygen consumption during walking using accelerometer-derived VM data from both the upper and lower limbs, along with walking velocity, and to identify a simplified model that balances accuracy and ease of implementation.

Materials and Methods

Participants

Eighteen healthy adults with regular exercise habits (nine men and nine women, aged 20–50 years) were recruited. Written informed consent was obtained from all participants. The study was approved by the Ethics Committee of Kyoto Tanabe Memorial Hospital (Approval No.: RBMR-220414) and conducted in accordance with the principles of the Declaration of Helsinki.

Protocol

Each participant performed treadmill walking at four different speeds: 3, 4, 5, and 6

121 km·h⁻¹ (up to 5.5 km·h⁻¹ for women). Each walking trial lasted 3 min, with data from

the final min used for analysis.

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Devices

Physical activity was measured using triaxial accelerometers (ActiGraph GT3X,

126 ActiGraph LLC, USA), attached with Velcro straps to both wrists and both ankles (four

sites). VO₂ was measured in real time using a portable breath-by-breath gas analyzer

128 (Aeromonitor AE-310S, Minato Medical Science, Japan). The average VO₂

129 (ml·kg⁻¹·min⁻¹) over the final min of each walking condition was calculated.

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Signal Processing

Raw acceleration data (30 Hz) were processed using ActiLife software (ver. 6.13.4,

133 ActiGraph LLC). VM was calculated after applying a normal filter (0.25–2.5 Hz) using

the following formula ll :

135 $VM = \sqrt{(X^2 + Y^2 + Z^2)}$

The resulting counts are dimensionless values derived from ActiGraph's proprietary algorithm and are widely used as indicators of physical activity intensity⁴⁾. In this study, the sum of VM from the right and left ankles was defined as FootVM, and the sum from both wrists as HandVM, expressed in counts·10⁻¹ s.

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Model Construction

- We aimed to develop a simple and accurate regression model to estimate VO₂
- 143 (ml·kg⁻¹·min⁻¹) based on accelerometer data. First, a comprehensive full model (Model
- 144 3) was developed using both upper and lower limb accelerometry data plus walking
- velocity, and the contribution and predictive performance of each variable were
- assessed.
- 147 The following four regression models were constructed and compared for predictive
- 148 accuracy:
- 1. Model 0: VO₂ ~ velocity (univariable model using velocity only)
- 2. Model 1: VO₂ ~ FootVM (univariable model using FootVM only)
- 3. Model 2: VO₂ ~ FootVM + velocity (two-variable model)
- 4. Model 3: VO₂ ~ FootVM + velocity + HandVM (three-variable full model)

Here, velocity was treated as a continuous variable representing the treadmill walking speed (km·h⁻¹) under each condition.

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Statistical Analysis

157 Descriptive statistics (mean \pm standard deviation) for participant characteristics (age, 158 height, body mass) were calculated separately for each sex. Between-group comparisons 159 were performed using independent two-sample *t*-tests. 160 Model performance was evaluated using the coefficient of determination (R²), standard 161 error of estimate (SEE), Akaike Information Criterion (AIC), and standardized 162 regression coefficients (βstd). A model improvement was considered meaningful when 163 \triangle AIC \leq -2. To assess multicollinearity among explanatory variables, the variance inflation factor (VIF) was calculated, with VIF < 5 considered acceptable. 164 165 To assess generalizability, subject-stratified five-fold cross-validation was performed, 166 and the mean SEE was calculated. Agreement between predicted and measured VO₂ 167 values was also evaluated using Bland-Altman analysis. All statistical analyses were 168 conducted using R (ver. 4.4.0) and EZR (ver. 1.52, Saitama Medical Center, Jichi 169 Medical University)¹²⁾. A significance level of p < 0.05 was adopted.

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171	Results
172	Participant Characteristics
173	Overall, 18 healthy adults (nine men, nine women; mean age 34.7 ± 8.3 years)
174	participated in the study. The mean height was 173.8 ± 2.5 cm for men and 158.8 ± 6.1
175	cm for women. Significant sex differences were observed in both height and body mass
176	(both $p < 0.05$; Table 1).
177	
178	Changes in Oxygen Consumption and Ankle Vector Magnitude by Speed
179	Both VO ₂ and FootVM increased progressively with walking speed conditions (very
180	slow, slow, middle, high), indicating a speed-dependent response load (Table 2). VO ₂
181	rose from $9.51 \pm 0.84~\text{ml} \cdot \text{kg}^{-1} \cdot \text{min}^{-1}$ in the very slow-speed group to
182	$16.29 \pm 1.78 \text{ ml} \cdot \text{kg}^{-1} \cdot \text{min}^{-1}$ in the high-speed group. Similarly, FootVM increased from
183	$8,344.76 \pm 1,137.64 \text{ counts} \cdot 10^{-1} \text{ s to } 16,843.69 \pm 2,945.44 \text{ counts} \cdot 10^{-1} \text{ s}.$
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Model Development and Comparison

- FootVM was significantly and positively correlated with VO₂ (r = 0.681, p < 0.001;
- Figure 1). To comprehensively capture physical movement, a three-variable model
- 188 (Model 3) including FootVM, walking velocity, and HandVM was first constructed.
- Model performance (Table 3) was as follows:
- 190 **Model 0** (velocity only): $R^2 = 0.786$, SEE = 1.34
- 191 **Model 1** (FootVM only): $R^2 = 0.464$, SEE = 2.10
- Model 2 (FootVM + velocity): $R^2 = 0.810$, SEE = 1.25, improved AIC (\triangle AIC =
- 193 -124.9)
- Model 3 (FootVM + velocity + HandVM): $R^2 = 0.815$, SEE = 1.24. However, β std
- for HandVM was -0.06 ($p \ge 0.05$), indicating minimal contribution. The AIC worsened
- compared with that of Model 2 (+18.4).
- 197 These findings suggest that upper limb acceleration (HandVM) does not significantly
- enhance the prediction of VO₂, and that Model 2 (FootVM + velocity) offers the most
- 199 practical and accurate estimation.
- In Model 2, the VIFs for FootVM and velocity were both 1.56, indicating no
- 201 multicollinearity concerns. An extended model including an interaction term between
- FootVM and velocity was also tested, but the addition of the interaction ($\beta = 0.00013$, p

203	< 0.001) did not improve model performance, and the AIC increased by $+13.2$.
204	The final selected model, Model 2, was as follows (Table 4):
205	$VO_2 \text{ (ml\cdot kg}^{-1} \cdot \text{min}^{-1}) = 1.563 + 0.00010 \times FootVM \text{ (counts} \cdot 10^{-1} \text{ s)} + 2.15 \times velocity$
206	(km·h ⁻¹)
207	This model achieved an R ² of 0.810 and SEE of 1.25 ml·kg ⁻¹ ·min ⁻¹ , meeting the
208	practical accuracy criterion of within ± 1 metabolic equivalent of task (MET; 3.5
209	$ml \cdot kg^{-1} \cdot min^{-1}$).
210	In both Models 2 and 3, β std for FootVM were negative (-0.877 and -0.764 ,
211	respectively), likely reflecting multicollinearity, where most of the explained variance
212	was absorbed by velocity. Indeed, the VIF for FootVM in Model 3 was slightly elevated
213	at 5.29.
214	However, in Model 1 (FootVM only), βstd was +1.964, showing a strong positive
215	contribution, indicating that FootVM remains a valuable independent predictor of VO ₂ .
216	
217	Linear Mixed-Effects Model and Cross-Validation
218	To account for inter-individual variability, a linear mixed-effects model was constructed
219	using FootVM and velocity as fixed effects and participant identity document as a

220 random effect. Both variables remained statistically significant predictors (FootVM: β = 0.00010, p < 0.001; velocity: $\beta = 2.15, p < 0.001$). 221 222 In subject-stratified five-fold cross-validation, the mean SEE was 223 $1.32 \pm 0.50 \,\mathrm{ml \cdot kg^{-1} \cdot min^{-1}}$, indicating no signs of overfitting and confirming the model's generalizability. 224 225 226 Bland-Altman Analysis 227 A Bland–Altman plot was created to compare measured and predicted VO₂ values, 228 showing a mean bias of 0.00 ml·kg⁻¹·min⁻¹, with 95% limits of agreement (LoA) 229 ranging from -2.46 to +2.46 ml·kg⁻¹·min⁻¹ (Figure 2). However, since this analysis was 230 conducted using the same dataset for both model development and evaluation, further 231 validation using independent datasets is warranted. 232 233 Comparison Between Predicted and Measured Oxygen Consumption 234 A scatter plot was created to compare predicted and measured VO₂ values, with data points color-coded by speed category, showing that most points were distributed closely 235 along the identity line (y = x). The overall coefficient of determination was $R^2 = 0.807$, 236

indicating high agreement (Figure 3).

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Discussion

In this preliminary study, we developed models to estimate VO₂ during walking using accelerations of the upper and lower limbs along with walking velocity, and statistically evaluated each variable's contribution. A key feature of this study is the structured model development process, beginning with a comprehensive full model including upper limb acceleration (HandVM; Model 3), and then rationally simplifying it to a two-variable model (Model 2) consisting of only lower limb acceleration (FootVM) and walking velocity. This simplification was not arbitrary; rather, it was based on quantitative evidence showing the limited contribution of HandVM to VO₂ estimation. FootVM alone showed a moderate correlation with VO_2 ($R^2 = 0.464$), but the addition of walking velocity improved the model considerably (Model 2: $R^2 = 0.810$, SEE = 1.25 ml·kg⁻¹·min⁻¹). Model 3, which included HandVM, slightly improved the fit (R² = 0.815, SEE = 1.24); however, β std for HandVM was -0.06 ($p \ge 0.05$), and the AIC was 18.4 points worse than that of Model 2. These findings suggest that HandVM does not significantly contribute to VO₂ prediction.

254 Model 2, consisting only of FootVM and velocity, achieved a practical balance between 255 accuracy and simplicity, reducing the burden of both sensor placement and data 256 processing. Prior studies have also pointed out that sensor location affects model accuracy. In particular, wrist acceleration is more prone to variability owing to non-257 periodic and individual-specific movements, making it less stable for VO₂ estimation 258 10,13). The current results support these previous observations. 259 260 Model 2 performance was comparable with that of conventional hip-worn models. For example, Freedson et al.⁴⁾ reported $R^2 = 0.82$ and $SEE = 1.40 \text{ kcal·min}^{-1}$, and Nichols et 261 262 al.⁵⁾ reported $R^2 = 0.68$ and $SEE = 2.5 \text{ ml} \cdot \text{kg}^{-1} \cdot \text{min}^{-1}$. In contrast, our Model 2 achieved $R^2 = 0.81$ and SEE = 1.25 ml·kg⁻¹·min⁻¹, using only FootVM and walking velocity, thus 263 264 demonstrating equal or superior predictive accuracy with a more minimalistic setup 265 (Table 5). Additionally, ankle-mounted sensors are less prone to displacement than are 266 waist-mounted ones, making them potentially more suitable for use in clinical and home settings $^{14)}$. 267 268 Bland–Altman analysis revealed a mean bias of 0.00 ml·kg⁻¹·min⁻¹ and LoA of ±2.46 269 ml·kg⁻¹·min⁻¹, well within the 1 MET threshold (3.5 ml·kg⁻¹·min⁻¹), indicating the 270 model's practical utility for physical activity monitoring and exercise prescription.

However, since this study was conducted under controlled treadmill conditions, its generalizability to free-living environments remains untested. Barnett et al.⁹⁾ reported that treadmill-based models can overestimate VO₂ by +4.99 ml·kg⁻¹·min⁻¹ in free-living conditions, highlighting how environmental differences can affect model accuracy.

Further validation in diverse settings and populations is therefore essential to enhance the model's applicability.

Collectively, the final model using FootVM and velocity is a statistically validated, simplified, and highly accurate estimator of VO₂, with promising potential for clinical and real-world applications.

Limitations

This study has some limitations. First, regarding the participant characteristics, the sample was limited to young to middle-aged healthy adults with exercise habits. The model's applicability to older adults or individuals with gait impairments remains unverified. Second, the study was conducted in a controlled environment, and all data were collected on a treadmill. The accuracy of the model in free-living conditions has not been evaluated. Previous studies have shown that models developed in laboratory

settings tend to overestimate VO₂ in free-living contexts⁹, which remains a challenge for real-world application. Third, the sensor placement: only sensors attached to the wrists and ankles were investigated in this study. Comparison with hip- or trunk-mounted sensors, which are commonly used in prior studies, was not conducted and warrants future investigation. Fourth, the model, which was intentionally kept simple, using only two predictors, FootVM and velocity, does not account for individual biomechanical differences such as height, body mass, or muscle strength, which may also influence VO₂. Lastly, the sample size: while cross-validation using the leave-one-subject-out method confirmed acceptable generalizability, the sample size (n = 18) was relatively small. Future studies should include larger and more diverse populations to evaluate external validity.

Conclusions

In this study, we initially developed a full model incorporating upper limb acceleration and quantitatively evaluated the contribution of each variable. Based on these analyses, we rationally derived a simplified two-variable model (Model 2) consisting of FootVM and walking velocity. This model demonstrated high predictive accuracy for VO_2 ($R^2 =$

305 0.810, SEE = 1.25 ml·kg⁻¹·min⁻¹), achieving a practical level of precision within the acceptable error range of less than 1 MET.

Notably, the addition of upper limb data did not lead to a significant improvement in prediction accuracy, indicating that the proposed model offers excellent wearability, simplicity, and reproducibility. These characteristics make it highly applicable in real-world settings. Future studies should explore its generalizability and feasibility in free-living environments and among clinical populations.

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Contributions

RN conceived and designed the study, conducted the experiments, analyzed the data,

interpreted the results, and wrote the manuscript. TI contributed to the study conception and design, provided guidance on data interpretation, and gave critical advice on data analysis and manuscript preparation. KO, HK, RI, and TH contributed to the execution of the study. SO and YM provided critical comments and advice on manuscript preparation. All authors reviewed and approved the final version of the manuscript.

Conflicts of Interest

The authors declare that there are no conflicts of interest.

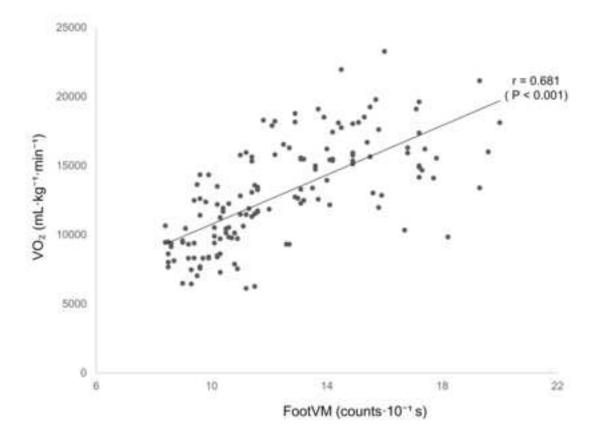
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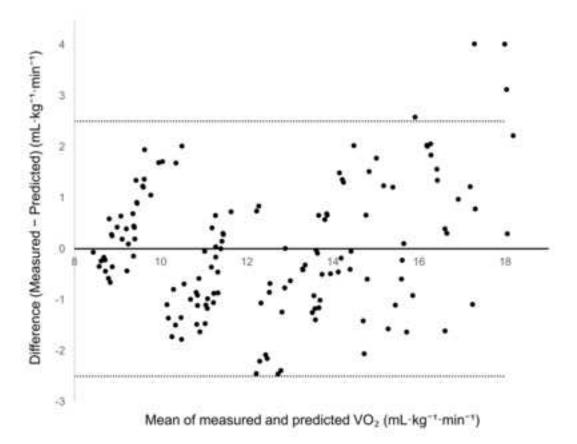
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375	Figure Legends
376	Figure 1. Relationship between FootVM and oxygen consumption per body mass (ml·
377	kg ⁻¹ ·min ⁻¹). Each point represents one trial. A significant positive correlation was
378	observed (r = 0.681, p < 0.001). VO ₂ , oxygen consumption; FootVM, vector magnitude
379	of both ankles.
380	
381	Figure 2. Bland–Altman plot showing the agreement between measured and predicted
382	VO ₂ (ml·kg ⁻¹ ·min ⁻¹). The solid line represents the mean difference (bias), and the dotted
383	lines indicate the limits of agreement (mean \pm 1.96 standard deviation). VO ₂ , oxygen
384	consumption.
385	
386	Figure 3. Scatter plot of predicted and observed VO ₂ (ml·kg ⁻¹ ·min ⁻¹) during treadmill
387	walking. The dashed line represents the line of identity $(y = x)$. Each marker indicates a
388	different walking speed category: + (very slow), \blacktriangle (slow), \times (middle), \bullet (high). VO ₂ ,
389	oxygen consumption.





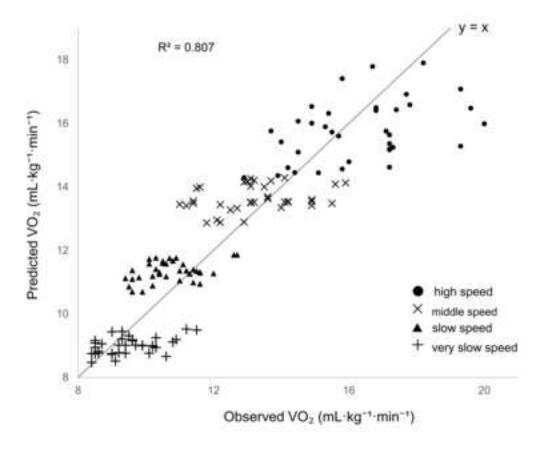


Table 1. Participant characteristics

	All (n = 18)	Males (n = 9)	Females (n = 9)	P-value (Male vs Female)
Age (years)	34.7 ± 8.3	33.6 ± 7.7	35.8 ± 8.7	0.51
Height (cm)	166.3 ± 8.8	173.8 ± 2.5	158.8 ± 6.1	< 0.05
Weight (kg)	61.3 ± 10.5	66.7 ± 9.8	55.9 ± 8.0	< 0.05

P-value: Two-sample t-test

Table 2. Changes in VO2 per body mass and FootVM at each speed

Speed	VO ₂ (ml·kg ⁻¹ ·min ⁻¹)	FootVM (counts·10 ⁻¹ s)
Very slow	9.51 ± 0.84	8344.76 ± 1137.64
Slow	10.72 ± 0.83	11558.88 ± 1369.06
Middle	13.22 ± 1.30	14975.10 ± 1752.17
High	16.29 ± 1.78	16843.69 ± 2945.44

FootVM: Vector magnitude of acceleration counts summed over 10 seconds, measured at both ankles; VO₂: Oxygen consumption.

Table 3. Comparison of regression models

	Explanatory		SEE	ΔΑΙC	
Model	Variables	R ²	(ml·kg ⁻¹ ·min ⁻¹)	(vs Model 1)	βstd
Model 0	velocity	0.786	1.34	-72.3	velocity: +2.556
Model 1	FootVM	0.464	2.1	0 (border)	FootVM: +1.964
Model 2	FootVM + velocity	0.81	1.25	-124.9	FootVM: -0.877 velocity: +3.309
Model 3	FootVM + velocity + HandVM	0.815	1.24	18.4	FootVM: -0.764 velocity: +3.330 HandVM: -0.162 (ns)

ns: not significant ($P \ge 0.05$). SEE: Standard Error of Estimate; β std: Standardized Regression

Coefficients; ΔAIC : Improvement in Akaike Information Criterion

Table 4. Regression equation of the final model (Model 2)

Variable	iable βstd SEE		95% Confidence Interval	P-value
intercept	1.563	0.4	0.76–2.36	< 0.001
FootVM	0.0001	0.00002	0.00006-0.00014	<0.001
velocity	2.15	0.12	1.91-2.39	<0.001

SEE: Standard Error of Estimate; \(\beta std: \) Standardized Regression Coefficients

Table 5. Comparison of model performance across previous studies and the present study

Study	Device Location	Environment	R ²	SEE
Freedson et al., 1998	Нір	Treadmill	0.82	1.40 kcal·min ⁻¹
Nichols et al., 2000	Hip	Treadmill	0.68	2.5 ml·kg ⁻¹ ·min ⁻¹
This study (Model 2)	Ankle + velocity	Treadmill	0.81	1.25 ml·kg ⁻¹ ·min ⁻¹

SEE: Standard Error of Estimate